



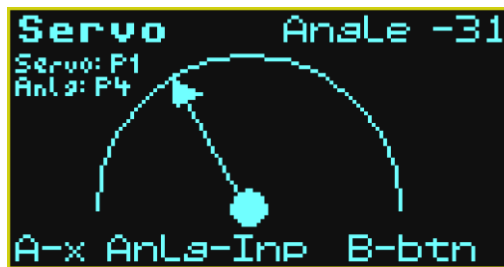
Servo App

This app demonstrates servo control using a Kookaberry and a lightweight micro servo. Two modes of operation are provided – one an incremental change of angle by using the buttons; and the other by continuously varying the angle via the potentiometer peripheral.

Setup

- Press a plastic servo arm onto the servo, lining it up with the long axis. This will be the vertical, or zero degree, reference point
- Plug a [Micro Servo](#) into P1 on the Kookaberry using a [JST PH to Breadboard Jumper \(3-pin\)](#). This will provide button control.
- Plug a [Potentiometer](#) into P4 (this will add analogue control)
- Navigate to the Servo app and press button B to run.

Running the App



What is showing on the two screens (Left one is Home screen)?

1. **Top Row:** Name of app and angle of servo arm
2. **Second and Third Rows:** Pin numbers for Servo and Analogue input (Potentiometer); Readout of angle of servo bar relative to vertical (zero degrees)
3. **Image:** Graphic of angle of servo arm.
 1. Set by buttons C and D when B on bottom row shows “anLg
 2. Set by analogue input (Potentiometer) when Button B is toggled to show “btn”
4. **Bottom Row:** **Button A** is Exit from app; **Buttons C & D** adjust angle in incremental steps; **Button B** toggles between button and analogue modes.